

Karush-Kuhn-Tucker Conditions with Inequality and Equality Constraints

For a problem in the following form,

$$\text{Min } f(\mathbf{x}) \quad (1)$$

$$\text{s.t. } g_i(\mathbf{x}) - b_i \geq 0 \quad i = 1, \dots, k \quad (2)$$

$$g_i(\mathbf{x}) - b_i = 0 \quad i = k+1, \dots, m \quad (3)$$

A) Give below the KT necessary conditions, explaining each equation.

Description	Equation	Applies to
Feasibility	$g_i(\mathbf{x}^*) - b_i$ is feasible $i = 1, \dots, m$	2,3
No direction which improves objective and is feasible	$\nabla f(\mathbf{x}^*) - \sum_{i=1}^m \lambda_i^* \nabla g_i(\mathbf{x}^*) = \mathbf{0}$	1-3 (all)
Complementary slackness	$\lambda_i^* [g_i(\mathbf{x}^*) - b_i] = 0 \quad i = 1, \dots, k$	2
Positive Lagrange multipliers	$\lambda_i^* \geq 0 \quad i = 1, \dots, k$	2

B) Solve for the optimum using the KKT conditions

$$\text{Min } f = 4x_1^2 + 2x_2^2$$

$$\text{s.t. } 3x_1 + x_2 = 8$$

$$2x_1 + 4x_2 \leq 15$$

Note: at the optimum, it is known that the inequality constraint is satisfied but not binding. Take advantage of this information.

Solution

$$3x_1 + x_2 - 8 = 0$$

$$-2x_1 - 4x_2 + 15 \geq 0$$

Not a binding constraint so $\lambda_2 = 0$ and we drop the inequality constraint.

$$\begin{bmatrix} 8x_1 \\ 6x_2 \end{bmatrix} - \lambda_1 \begin{bmatrix} 3 \\ 1 \end{bmatrix} - 0 \begin{bmatrix} -2 \\ -4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\underline{A} := \begin{pmatrix} 3 & 1 & 0 \\ 8 & 0 & -3 \\ 0 & 6 & -1 \end{pmatrix} \quad \underline{b} := \begin{pmatrix} 8 \\ 0 \\ 0 \end{pmatrix} \quad \underline{x} := \underline{A}^{-1} \cdot \underline{b} \quad \underline{x} = \begin{pmatrix} 2.323 \\ 1.032 \\ 6.194 \end{pmatrix}$$

C) For the following problem,

$$\begin{aligned} \text{Min} \quad & f = x_1^2 + x_2 \\ \text{s.t.} \quad & g_1 = x_1^2 + x_2^2 - 9 \leq 0 \\ & g_2 = x_1 + x_2 - 1 \leq 0 \quad ++ \end{aligned}$$

Show that the point [1,0] does not satisfy the KKT conditions

1 – Check feasibility of all equations

$$x_1 := 1 \quad x_2 := 0$$

$$x_1^2 + x_2^2 - 9 = -8 \quad \text{This is less than or equal to zero - passes test}$$

$$x_1 + x_2 - 1 = 0 \quad \text{This is less than or equal to zero - passes test}$$

Translate Inequality Constraints to Standard Form

$$g_1 = -x_1^2 - x_2^2 + 9 \geq 0$$

$$g_2 = -x_1 - x_2 + 1 \geq 0$$

Calculate Lagrange multipliers

$$\begin{pmatrix} 2 \cdot x_1 \\ 1 \end{pmatrix} - \lambda_1 \begin{pmatrix} -2 \cdot x_1 \\ -2 \cdot x_2 \end{pmatrix} - \lambda_2 \begin{pmatrix} -1 \\ -1 \end{pmatrix} = 0$$

$$\text{with } x_1 = 1 \text{ and } x_2 = 0$$

$$\begin{pmatrix} 2 & 1 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} = \begin{pmatrix} -2 \\ -1 \end{pmatrix}$$

$$\lambda_2 := -1 \quad 2 \cdot \lambda_1 + \lambda_2 = -2 \quad \lambda_1 = -\frac{1}{2}$$

$$\lambda_1 < 0 \quad \text{and}$$

$$\lambda_2 < 0 \quad \text{violate KKT condition \#4}$$

Set $\lambda_1=0$ and re-evaluate because contour plot shows that constraint #1 is not active:

However, when this is performed, $\lambda_2=-2$ and $\lambda_2=-1$ result from KKT condition #2 equations and a consistent set of Lagrange multipliers cannot be obtained. Therefore, it is not at the optimal solution.

