Response of First Order Systems

$$X(s) \longrightarrow G(s) = \frac{K}{\tau s + 1} \longrightarrow Y(s)$$

First Order Functions

• Time Domain

$$\tau \frac{dy}{dt} + y = Kx$$

Laplace Domain

$$\frac{Y(s)}{X(s)} = G(s) = \frac{K}{\tau s + 1}$$

Input Functions (i.e., X(s))

Step	$u(s) = \frac{M}{s}$	(5-6)	
Ramp	$u(s) = \frac{a}{s^2}$	(5-8)	
Rectangular pulse	$u(s) = \frac{h}{s} \left(1 - e^{-t_w s} \right)$	(5-11)	
Triangular pulse	$u(s) = \frac{2}{t_w} \left(\frac{1 - 2e^{-t_w s/2} + e^{-t_w s}}{s^2} \right)$	(5-13)	(slope=t _w /2)
Sine wave	$u(s) = \frac{A\omega}{s^2 + \omega^2}$	(5-15)	
Impulse	u(s) = a	p. 76	

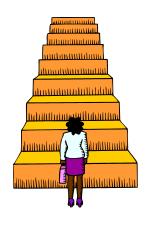
Response to Step

$$Y(s) = X(s)G(s)$$

$$X(s) = \frac{M}{s}$$

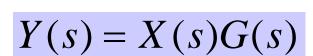
$$G(s) = \frac{K}{\tau s + 1}$$

$$Y(s) = \frac{KM}{s(\tau s + 1)}$$



$$y(t) = KM \left(1 - e^{-t/\tau}\right)$$
(5-18)

Response to Ramp



$$X(s) = \frac{a}{s^2}$$

$$G(s) = \frac{K}{\tau s + 1}$$

$$Y(s) = \frac{Ka}{s^2(\tau s + 1)}$$



$$y(t) = Ka\tau(e^{-t/\tau} - 1) + Kat$$
(5-22)





$$Y(s) = X(s)G(s)$$

$$X(s) = \frac{A\omega}{s^2 + \omega^2}$$

$$G(s) = \frac{K}{\tau s + 1}$$

$$Y(s) = \frac{KA\omega}{(s^2 + \omega^2)(\tau s + 1)} = KA\omega \left[\frac{a}{\tau s + 1} + \frac{bs + c}{s^2 + \omega^2} \right]$$

$$y(t) = \frac{Ka}{\omega^2 \tau^2 + 1} \left(\omega \tau e^{-t/\tau} - \omega \tau \cos \omega t + \sin \omega t \right)$$
 (5-25)

Time Delays (θ)

In time domain:

• Replace t with $(t-\theta)$ and multiply by $S(t-\theta)$

$$f(t-\theta)\cdot S(t-\theta)$$

In Laplace domain

• Multiply by e^{-θs}

$$e^{-\theta s}F(s)$$

Example: FOPDT

- This is a response of a first order model to a step function M
- First order with a step function is:

$$Y(s) = \frac{KM}{s(\tau s + 1)}$$

$$y(t) = KM \left(1 - e^{-t/\tau}\right)$$

Now add time delay

$$Y(s) = \frac{KM \cdot e^{-\theta s}}{s(\tau s + 1)}$$

$$y(t) = KM \left(1 - e^{-(t - \theta)/\tau}\right) \cdot S(t - \theta)$$

Pumped Tank Example

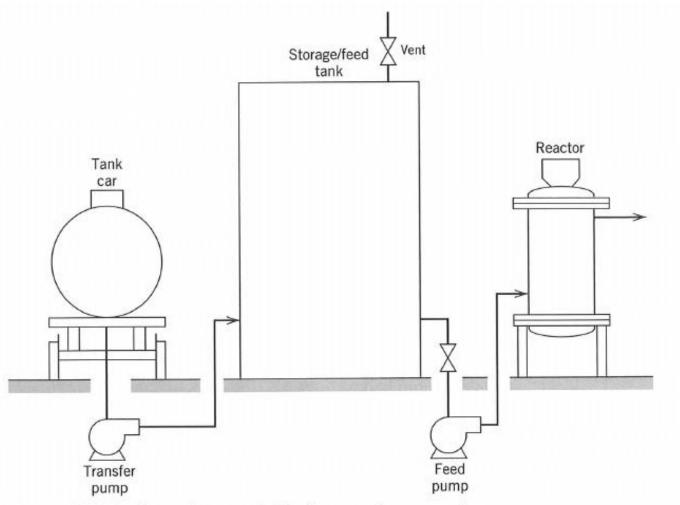


Figure 5.6 Unloading and storage facility for a continuous reactor.

Integrating Process

Pumped Tank

$$A\frac{dh}{dt} = q_i - q$$

$$sAH'(s) = Q_i'(s) - Q'(s)$$

$$H'(s) = \frac{1}{sA} [Q_i'(s) - Q'(s)]$$

$$\frac{H'(s)}{Q_i'(s)} = \frac{1}{sA}$$

$$\frac{H'(s)}{Q'(s)} = -\frac{1}{sA}$$

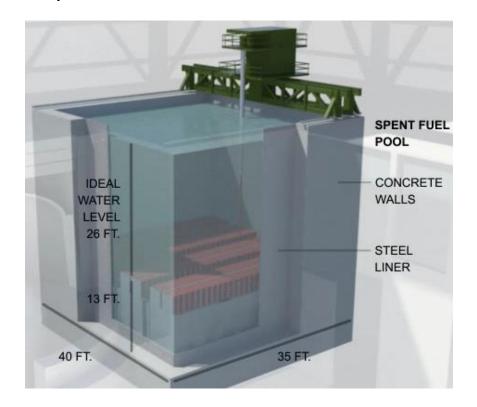
- This is not a first order model
- Called an integrating process (no steady-state gain)
- Step function in q or q_i results in ramp in h

$$Q_i'(s) = \frac{M}{s}$$

$$H'(s) = \frac{M}{s^2 A}$$

Fukushima Application

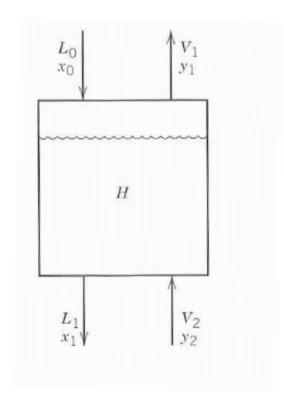
How long until the water level reaches the spent nuclear fuel rods if the power is shut off? When the spent nuclear fuel was exposed after 3 1/2 days, was there likely a leak caused by the earthquake or was the level loss due only to vaporization?





Problem 4.7 – Distillation Stage

H is molar holdup, L and V are molar flow rates y's and x's are mole fractions in vapor and liquid



Stirred tank blending system (or stage on distillation column)

Wanted:

$$\frac{X_1'(s)}{X_0'(s)} \quad \frac{X_1'(s)}{Y_2'(s)} \quad \frac{Y_1'(s)}{X_0'(s)} \quad \frac{Y_1'(s)}{Y_2'(s)}$$

• Given:

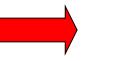
$$\begin{split} \frac{dH}{dt} &= L_0 + V_2 - \left(L_1 + V_1\right) \\ \frac{dx_1 H}{dt} &= x_0 L_0 + y_2 V_2 - \left(x_1 L_1 + y_1 V_1\right) \\ y_1 &= a_0 + a_1 x_1 + a_2 x_1^2 + a_3 x_1^3 \\ &\text{Vapor / Liquid composition correlation} \end{split}$$

Assumptions

Molar holdup H is constant

$$\frac{dH}{dt} = 0$$

Constant molal overflow



$$L_0 = L_1$$

$$V_1 = V_2$$

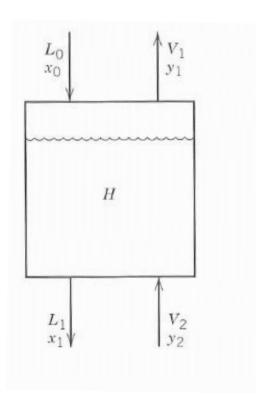
• Simplification: only use *L* and *V* (no subscripts)

$$\frac{dx_1H}{dt} = x_0L + y_2V - (x_1L + y_1V)$$

$$y_1 = a_0 + a_1x_1 + a_2x_1^2 + a_3x_1^3$$

Distillation Stage

$$\frac{dx_1H}{dt} = x_0L + y_2V - (x_1L + y_1V)$$
$$y_1 = a_0 + a_1x_1 + a_2x_1^2 + a_3x_1^3$$



$$\frac{X_1'(s)}{X_0'(s)}$$



$$\frac{Y_1'(s)}{X_0'(s)}$$

$$\frac{Y_1'(s)}{Y_2'(s)}$$